

L Number	Hits	Search Text	DB	Time stamp
-	89	702/\$.ccls. and (position same orientation same data) and (sens\$3 with position) and target	USPAT; US-PGPUB	2004/10/28 17:28
-	10	(702/\$.ccls. and (position same orientation same data) and (sens\$3 with position) and target) and (transmit\$6 with control with signal)	USPAT; US-PGPUB	2004/10/30 14:31
-	2	702/\$.ccls. and (position same orientation same data) and (identif\$4 with target with device)	USPAT; US-PGPUB	2004/09/26 12:19
-	0	(702/\$.ccls. and (position same orientation same data) and (identif\$4 with target with device) ) and (transmit\$6 with control with signal)	USPAT; US-PGPUB	2004/09/26 12:14
-	0	(702/\$.ccls. and (position same orientation same data) and (identif\$4 with target with device) ) and ( control with signal)	USPAT; US-PGPUB	2004/09/26 12:14
-	10	702/\$.ccls. and (position same orientation same data) and (identif\$4 with target with location)	USPAT; US-PGPUB	2004/09/26 12:23
-	1	10/010104	USPAT; US-PGPUB	2004/09/26 12:25
-	1	5963145.pn.	USPAT; US-PGPUB	2004/09/26 12:25
-	0	(702/\$.ccls. and (position same orientation same data) and (sens\$3 with position) and target) and (transmit\$6 with control with signal) and (identif\$4 with target with location)	USPAT; US-PGPUB	2004/09/26 13:27
-	1	(702/\$.ccls. and (position same orientation same data) and (identif\$4 with target with location) and (control\$3 with signal))	USPAT; US-PGPUB	2004/09/26 13:35
-	11	702/\$.ccls. and (position same orientation same data) and ( three-dimensional or 3D) with Cartesian)	USPAT; US-PGPUB	2004/09/26 13:37
-	5	(702/\$.ccls. and (position same orientation same data) and ( three-dimensional or 3D) with Cartesian)) and RF	USPAT; US-PGPUB	2004/09/26 13:37
-	66	((electronic near2 appliance) (air adj condition) television (stereo near2 sound near2 system) photocop\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:43
-	3	((electronic near2 appliance) (air adj condition) television (stereo near2 sound near2 system) photocop\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (stor\$3 with location with information)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:44
-	3	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocop\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (stor\$3 with location with information)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:44
-	66	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocop\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:47

-	43	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocopy\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (network\$3 with device)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:47
-	40	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocopy\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (network\$3 with device)) and (control\$3 with signal) and (user with input\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:48
-	1	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocopy\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (network\$3 with device)) and (control\$3 with signal) and (user with input\$3)) and (sens\$3 with orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:49
-	40	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocopy\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (network\$3 with device)) and (control\$3 with signal) and (user with input\$3)) and target	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:49
-	1	((electronic near2 appliance) (air adj condition\$3) television (stereo near2 sound near2 system) photocopy\$4 printer (screen near2 display)) and (RF (radio near2 frequency) (communication near2 cable)) and (workstation (mobile near2 terminal) (personal near2 digital near2 assistant) PDA handheld) and controller and (point\$3 with alignment) and (sensor with position) and orientation) and (network\$3 with device)) and (control\$3 with signal) and (user with input\$3)) and target) and (select\$3 with target)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 17:57
-	1	target and (sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (position with data) same orientation same (user with input\$3)) and communication and controller	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 18:00
-	1	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (position with data) same orientation same (user with input\$3)) and communication and controller	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 18:01
-	6	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (position with data) same orientation same (user with input\$3)) and communication and (controller CPU computer microcomputer)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 13:01

-	1	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (position with data) same orientation same (user with input\$3)) and communication and (controller CPU computer microcomputer)) and target	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 15:13
-	1	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (position with data) same orientation same (user with input\$3)) and communication and (controller CPU computer microcomputer)) and network\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/28 18:02
-	2	5963145.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 15:08
-	1	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (position with data) same orientation same (user with input\$3)) and (IR with communication) and (controller CPU computer microcomputer))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 15:14
-	9	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (IR with communication) and (controller CPU computer microcomputer))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:44
-	224	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (controller CPU computer microcomputer)) and gyroscope	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 16:16
-	97	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (controller CPU computer microcomputer)) and gyroscope) and ((sens\$3 with orientation) same gyroscope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 16:17
-	35	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (controller CPU computer microcomputer)) and gyroscope) and ((sens\$3 with orientation) same gyroscope)) and point\$3 and target	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 16:17
-	3	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (controller CPU computer microcomputer)) and gyroscope) and ((sens\$3 with orientation) same gyroscope)) and point\$3 and target) and (point with shape)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 16:40
-	9	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (controller CPU computer microcomputer)) and gyroscope) and ((sens\$3 with orientation) same gyroscope)) and point\$3 and target) and (select\$3 with target)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 16:40
-	34	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:45
-	1	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope) and (point\$3 with shape)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:46

-	28	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope) and point\$3 and target	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:48
-	1	((((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope) and point\$3 and target) and (point\$3 with print\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:47
-	27	((((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope) and point\$3 and target) and wireless	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:48
-	24	(((((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope) and point\$3 and target) and wireless) and (RF or (radio near2 frequency)))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:50
-	0	(((((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (control\$3 with signal) and (user with input\$3) and (infrared with communication) and gyroscope) and point\$3 and target) and wireless) and (RF or (radio near2 frequency)))) and (robot with arm)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:50
-	0	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (point\$3 with shape) and (robot with arm) and (infrared with communication) and gyroscope	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 17:52
-	7	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and point\$3 and (robot with arm) and (infrared with communication) and gyroscope	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:10
-	0	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (robot with arm) and (infrared with communication) and (gyroscope with orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:11
-	0	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (robot with arm) and (infrared with communication) and (gyroscope same orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:12
-	0	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (robot\$6 with arm) and (infrared with communication) and (gyroscope same orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:12
-	0	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and robot\$6 and (infrared with communication) and (gyroscope same orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:12
-	24	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (gyroscope same orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:20

-	95	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (point\$3 same display\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:54
-	16	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (point\$3 same display\$3) and (point\$3 same print\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:09
-	45	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (point\$3 with display\$3) and (point\$3 with print\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 18:56
-	2	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (point\$3 with display\$3) and (point\$3 with print\$3)) and (infrared with communication)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:16
-	26	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (point\$3 with display\$3) and (point\$3 with print\$3)) and infrared and communication	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:07
-	18	("5963145" "5650831" "6078575" "6028764" "5880867" "5767807" "4959721" "5528264" "5506717").pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 14:31
-	0	((("5963145" "5650831" "6078575" "6028764" "5880867" "5767807" "4959721" "5528264" "5506717").pn.) and (point\$3 same display\$3) and (point\$3 same print\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 14:30
-	13	((("5963145" "5650831" "6078575" "6028764" "5880867" "5767807" "4959721" "5528264" "5506717").pn.) and point\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:40
-	67	(sens\$3 with position) and (sens\$3 with orientation) and (point\$3 with display\$3) and (point\$3 with print\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:16
-	3	((sens\$3 with position) and (sens\$3 with orientation) and (point\$3 with display\$3) and (point\$3 with print\$3)) and (infrared with communication)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:17
-	35	((sens\$3 with position) and (sens\$3 with orientation) and (point\$3 with display\$3) and (point\$3 with print\$3)) and infrared and communication	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:17
-	0	((("5963145" "5650831" "6078575" "6028764" "5880867" "5767807" "4959721" "5528264" "5506717").pn.) and angle and dimensional	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:41

-	0	((("5963145" "5650831" "6078575" "6028764" "5880867" "5767807" "4959721" "5528264" "5506717").pn.) and angle and axes)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:41
-	1	((("5963145" "5650831" "6078575" "6028764" "5880867" "5767807" "4959721" "5528264" "5506717").pn.) and angle and axes)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/29 19:41
-	119	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 12:09
-	92	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:28
-	32	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and (network\$3 with device)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:55
-	33	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and gyroscope	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:57
-	29	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and gyroscope) and RF	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:57
-	39	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and gyro\$6 and point\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:57
-	32	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and gyro\$6 and point\$3) and RF	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:57
-	26	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and gyro\$6 and point\$3) and RF) and target	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:58
-	26	((sens\$3 with position) and (sens\$3 with orientation) and (position with data) and (infrared with communication) and (control\$3 with signal) and (transmit\$6 with signal)) and controller) and gyro\$6 and point\$3) and RF) and target) and wireless	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 11:58
-	161	(target with control\$3 with signal) and (sens\$3 with position) and (sens\$3 with orientation) and (position with data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 12:11

-	31	((target with control\$3 with signal) and (sens\$3 with position) and (sens\$3 with orientation) and (position with data) ) and (transmit\$3 with signal) and infrared	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 12:12
-	0	(702/\$.ccls. and (position same orientation same data) and (sens\$3 with position) and target) and (transmit\$6 adj5 control adj1 signal)	USPAT; US-PGPUB	2004/10/30 12:53
-	6	(702/\$.ccls. and (position same orientation same data) and (sens\$3 with position) and (sens\$3 with orientation)) and (transmit\$6 adj5 control adj1 signal)	USPAT; US-PGPUB	2004/10/30 12:54
-	7	(702/\$.ccls. and (position with data) and (sens\$3 with position) and (sens\$3 with orientation)) and (transmit\$6 adj5 control adj1 signal)	USPAT; US-PGPUB	2004/10/30 12:55
-	14	(702/\$.ccls. and (position with data) and (sens\$3 with position) and (sens\$3 with orientation)) and (transmit\$6 with (control adj1 signal))	USPAT; US-PGPUB	2004/10/30 12:56
-	36	(sens\$3 with position) and (sens\$3 with orientation) and (position with data) and ((control\$3 with signal) same (user with input\$3)) and communication and (transmit\$6 with control\$3 with signal) and (controller CPU computer microcomputer)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 13:57
-	2	6289263.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/30 13:57
-	1	4959721.pn.	USPAT; US-PGPUB	2004/10/30 14:32